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Commit ca1a66f



aligungr committed 2 weeks ago

Security hardening for Radio Link Simulation (RLS) layer.

master · v3.2.8

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```

@@ -2,7 +2,7 @@
2 2     <a href="https://github.com/aligungr/UERANSIM"></a>
3 3     </p>
4 4     <p align="center">
5 5     - 
6 6     + 
7 7     
8 8     
9 9     </p>
@@ -13,9 +13,6 @@ testing 5G Core Network and studying 5G System.
13 13
14 14     UERANSIM introduces the world's first open source 5G-SA UE and gNodeB
    implementation.
15 15
16 16     - > [!IMPORTANT]
17 17     - > UERANSIM is no longer actively developed by the maintainer. However community
    contributions are welcomed.
18 18     -
19 16     ## Current Status
20 17
21 18     Basic functionalities of UE and gNodeB are fully functional and ready to use.
    However some of the features are not complete.
@@ -33,8 +30,7 @@ On the other hand, UERANSIM does not fully provide physical
    layer. 5G-NR radio i
33 30
34 31     You can find the documentation on [UERANSIM Wiki]
    (https://github.com/aligungr/UERANSIM/wiki).
35 32
36 32     - And, since the project is rapidly developing, please make sure that you have
    always
37 32     - the [latest](https://github.com/aligungr/UERANSIM/releases) UERANSIM.
38 33     + And, please make sure that you have always the [latest]
    (https://github.com/aligungr/UERANSIM/releases) UERANSIM.
39 34
40 35     ## Contributing

```

```

40 36
@@ -50,7 +46,7 @@ You can support UERANSIM by:
50 46
51 47 ## License
52 48
53 - Copyright (c) 2025 ALI GÜNGÖR.
49 + Copyright (c) 2026 ALI GÜNGÖR.
54 50
55 51 All source code and related files including documentation and wiki pages are
56 52 dual licensed with [AGPL-3.0](https://www.gnu.org/licenses/agpl-3.0.en.html) and
a commercial license.

```

```

src/gnb/rls/ctl_task.cpp
@@ -123,7 +123,7 @@ void RlsControlTask::handleRlsMessage(int ueId,
rls::RlsMessage &msg)
123 123     else if (msg.msgType == rls::EMessageType::PDU_TRANSMISSION)
124 124     {
125 125         auto &m = (rls::RlsPduTransmission &)msg;
126 -     if (m.pduId != 0)
126 +     if (m.pduId != 0 && m_pendingAck[ueId].size() < MAX_PDU_COUNT)
127 127         m_pendingAck[ueId].push_back(m.pduId);
128 128
129 129         if (m.pduType == rls::EPduType::DATA)
@@ -136,6 +136,12 @@ void RlsControlTask::handleRlsMessage(int ueId,
rls::RlsMessage &msg)
136 136     }
137 137     else if (m.pduType == rls::EPduType::RRC)
138 138     {
139 +         if (m.payload > static_cast<uint32_t>(rrc::RrcChannel::UL_DCCH))
140 +         {
141 +             m_logger->err("Invalid RRC channel value: %d", m.payload);
142 +             return;
143 +         }
144 +
139 145         auto w = std::make_unique<NmGnbRlsToRls>
(NmGnbRlsToRls::UPLINK_RRC);
140 146         w->ueId = ueId;
141 147         w->rrcChannel = static_cast<rrc::RrcChannel>(m.payload);

```

```

↑... @@ -240,12 +246,12 @@ void RlsControlTask::onAckControlTimerExpired()
240 246
241 247 void RlsControlTask::onAckSendTimerExpired()
242 248 {
243 - auto copy = m_pendingAck;
249 + auto copy = std::move(m_pendingAck);
244 250 m_pendingAck.clear();
245 251
246 252 for (auto &item : copy)
247 253 {
248 - if (!item.second.empty())
254 + if (item.second.empty())
249 255 continue;
250 256
251 257 rls::RlsPduTransmissionAck msg{m_sti};
↓...

```

```

src/gnb/rls/udp_task.cpp
↑... @@ -26,13 +26,16 @@ static constexpr const int HEARTBEAT_THRESHOLD = 2000;
// (LOOP_PERIOD + RECEIVE
26 26
27 27 static constexpr const int MIN_ALLOWED_DBM = -120;
28 28
29 + static constexpr const size_t MAX_UE_COUNT = 1024;
30 +
29 31 static int EstimateSimulatedDbm(const Vector3 &myPos, const Vector3 &uePos)
30 32 {
31 - int deltaX = myPos.x - uePos.x;
32 - int deltaY = myPos.y - uePos.y;
33 - int deltaZ = myPos.z - uePos.z;
33 + double deltaX = static_cast<double>(myPos.x) - static_cast<double>
(uePos.x);
34 + double deltaY = static_cast<double>(myPos.y) - static_cast<double>
(uePos.y);
35 + double deltaZ = static_cast<double>(myPos.z) - static_cast<double>
(uePos.z);
34 36
35 - int distance = static_cast<int>(std::sqrt(deltaX * deltaX + deltaY * deltaY
+ deltaZ * deltaZ));
37 + double distSq = deltaX * deltaX + deltaY * deltaY + deltaZ * deltaZ;

```

```

38 +     int distance = static_cast<int>(std::sqrt(distSq));
36 39     if (distance == 0)
37 40         return -1; // 0 may be confusing for people
38 41     return -distance;
@@ -109,9 +112,16 @@ void RlsUdpTask::receiveRlsPdu(const InetAddress &addr,
std::unique_ptr<rls::Rls
109 112     }
110 113     else
111 114     {
115 +         if (m_ueMap.size() >= MAX_UE_COUNT)
116 +         {
117 +             m_logger->warn("Max UE count reached, rejecting new UE");
118 +             return;
119 +         }
120 +
112 121         int ueId = ++m_newIdCounter;
113 122
114 123         m_stiToUe[msg->sti] = ueId;
124 +         m_ueMap[ueId].sti = msg->sti;
115 125         m_ueMap[ueId].address = addr;
116 126         m_ueMap[ueId].lastSeen = utils::CurrentTimeMillis();
117 127

```

```

src/lib/rls/rls_pdu.cpp
@@ -54,6 +54,10 @@ void EncodeRlsMessage(const RlsMessage &msg, OctetString
&stream)
54 54
55 55     std::unique_ptr<RlsMessage> DecodeRlsMessage(const OctetView &stream)
56 56     {
57 +         // Minimum header: 1 (compat) + 3 (version) + 1 (msgType) + 8 (sti) = 13
bytes
58 +         if (stream.remainingSize() < 13)
59 +             return nullptr;
60 +
57 61         auto first = stream.readI(); // (Just for old RLS compatibility)
58 62         if (first != 3)
59 63             return nullptr;
@@ -66,10 +70,19 @@ std::unique_ptr<RlsMessage> DecodeRlsMessage(const
OctetView &stream)

```

```

66 70         return nullptr;
67 71
68 72         auto msgType = static_cast<EMessageType>(stream.readI());
73 +
74 +         // Validate message type before reading further
75 +         if (msgType != EMessageType::HEARTBEAT && msgType !=
EMessageType::HEARTBEAT_ACK &&
76 +             msgType != EMessageType::PDU_TRANSMISSION && msgType !=
EMessageType::PDU_TRANSMISSION_ACK)
77 +             return nullptr;
78 +
69 79         uint64_t sti = stream.read8UL();
70 80
71 81         if (msgType == EMessageType::HEARTBEAT)
72 82         {
83 +             // Need 12 bytes (3 x int32)
84 +             if (stream.remainingSize() < 12)
85 +                 return nullptr;
73 86         auto res = std::make_unique<RlsHeartBeat>(sti);
74 87         res->simPos.x = stream.read4I();
75 88         res->simPos.y = stream.read4I();
@@ -78,28 +91,54 @@ std::unique_ptr<RlsMessage> DecodeRlsMessage(const
OctetView &stream)
78 91     }
79 92     else if (msgType == EMessageType::HEARTBEAT_ACK)
80 93     {
94 +         // Need 4 bytes (int32)
95 +         if (stream.remainingSize() < 4)
96 +             return nullptr;
81 97         auto res = std::make_unique<RlsHeartBeatAck>(sti);
82 98         res->dbm = stream.read4I();
83 99         return res;
84 100     }
85 101     else if (msgType == EMessageType::PDU_TRANSMISSION)
86 102     {
103 +         // Need 1 (pduType) + 4 (pduId) + 4 (payload) + 4 (pduLength) = 13
bytes minimum
104 +         if (stream.remainingSize() < 13)
105 +             return nullptr;
106 +

```

```

87 107         auto res = std::make_unique<RlsPduTransmission>(sti);
88 -         res->pduType = static_cast<EPduType>((uint8_t)stream.read());
108 +         auto rawPduType = static_cast<uint8_t>(stream.read());
109 +         if (rawPduType != static_cast<uint8_t>(EPduType::RRC) &&
110 +             rawPduType != static_cast<uint8_t>(EPduType::DATA))
111 +             return nullptr;
112 +         res->pduType = static_cast<EPduType>(rawPduType);
113 +
89 114         res->pduId = stream.read4UI();
90 115         res->payload = stream.read4UI();
91 116
92 -         int pduLength = stream.read4I();
117 +         uint32_t pduLength = stream.read4UI();
93 118         if (pduLength > 16384)
94 119             return nullptr;
95 -
96 -         res->pdu = stream.readOctetString(pduLength);
120 +         if (stream.remainingSize() < pduLength)
121 +             return nullptr;
122 +
123 +         res->pdu = stream.readOctetString(static_cast<int>(pduLength));
97 124         return res;
98 125     }
99 126     else if (msgType == EMessageType::PDU_TRANSMISSION_ACK)
100 127     {
128 +         static constexpr uint32_t MAX_ACK_COUNT = 4096;
129 +
130 +         // Need 4 bytes for count
131 +         if (stream.remainingSize() < 4)
132 +             return nullptr;
133 +
101 134         auto res = std::make_unique<RlsPduTransmissionAck>(sti);
102 135         auto count = stream.read4UI();
136 +         if (count > MAX_ACK_COUNT)
137 +             return nullptr;
138 +         // Need count * 4 bytes for pduIds
139 +         if (stream.remainingSize() < static_cast<size_t>(count) * 4)
140 +             return nullptr;
141 +
103 142         res->pduIds.reserve(count);

```

```

104 143         for (uint32_t i = 0; i < count; i++)
105 144             res->pduIds.push_back(stream.read4UI());

```



src/ue/rls/ctl_task.cpp



```

@@ -108,7 +108,7 @@ void RlsControlTask::handleRlsMessage(int cellId,
rls::RlsMessage &msg)

```

```

108 108         else if (msg.msgType == rls::EMessageType::PDU_TRANSMISSION)
109 109             {
110 110                 auto &m = (rls::RlsPduTransmission &)msg;
111 111                 - if (m.pduId != 0)
111 111                 + if (m.pduId != 0 && m_pendingAck[cellId].size() < MAX_PDU_COUNT)
112 112                     m_pendingAck[cellId].push_back(m.pduId);
113 113
114 114                 if (m.pduType == rls::EPduType::DATA)

```



```

@@ -127,6 +127,12 @@ void RlsControlTask::handleRlsMessage(int cellId,
rls::RlsMessage &msg)

```

```

127 127             }
128 128             else if (m.pduType == rls::EPduType::RRC)
129 129             {
130 130                 + if (m.payload > static_cast<uint32_t>(rrc::RrcChannel::UL_DCCH))
131 131                 + {
132 132                     m_logger->err("Invalid RRC channel value: %d", m.payload);
133 133                     return;
134 134                 + }
135 135                 +

```

```

130 136                 auto w = std::make_unique<NmUeRlsToRls>
(NmUeRlsToRls::DOWNLINK_RRC);
131 137                 w->cellId = cellId;
132 138                 w->rrcChannel = static_cast<rrc::RrcChannel>(m.payload);

```



```

@@ -233,12 +239,12 @@ void RlsControlTask::onAckControlTimerExpired()

```

```

233 239
234 240     void RlsControlTask::onAckSendTimerExpired()
235 241     {
236 241         - auto copy = m_pendingAck;
242 242         + auto copy = std::move(m_pendingAck);
237 243         m_pendingAck.clear();
238 244
239 245         for (auto &item : copy)

```

```

240 246      {
241 -      if (!item.second.empty())
247 +      if (item.second.empty())
242 248          continue;
243 249
244 250      rls::RlsPduTransmissionAck msg{m_shCtx->sti};

```



src/ue/rls/udp_task.cpp



```

↑... @@ -21,6 +21,8 @@ static constexpr const int LOOP_PERIOD = 1000;
21 21  static constexpr const int RECEIVE_TIMEOUT = 200;
22 22  static constexpr const int HEARTBEAT_THRESHOLD = 2000; // (LOOP_PERIOD +
    RECEIVE_TIMEOUT)'dan büyük olmalı
23 23
24 + static constexpr const size_t MAX_CELL_COUNT = 256;
25 +
24 26  namespace nr::ue
25 27  {
26 28
↓...
↑... @@ -93,6 +95,12 @@ void RlsUdpTask::receiveRlsPdu(const InetAddress &addr,
    std::unique_ptr<rls::Rls
93 95      {
94 96          if (!m_cells.count(msg->sti))
95 97      {
98 +          if (m_cells.size() >= MAX_CELL_COUNT)
99 +          {
100 +              m_logger->warn("Max cell count reached, ignoring new cell");
101 +              return;
102 +          }
103 +
96 104          m_cells[msg->sti].cellId = ++m_cellIdCounter;
97 105          m_cellIdToSti[m_cells[msg->sti].cellId] = msg->sti;
98 106      }

```



src/utils/constants.hpp



```

↑... @@ -15,10 +15,10 @@ struct cons
15 15      // Version information
16 16      static constexpr const uint8_t Major = 3;

```

```

17 17      static constexpr const uint8_t Minor = 2;
18 -      static constexpr const uint8_t Patch = 7;
18 +      static constexpr const uint8_t Patch = 8;
19 19      static constexpr const char *Project = "UERANSIM";
20 -      static constexpr const char *Tag = "v3.2.7";
21 -      static constexpr const char *Name = "UERANSIM v3.2.7";
20 +      static constexpr const char *Tag = "v3.2.8";
21 +      static constexpr const char *Name = "UERANSIM v3.2.8";
22 22      static constexpr const char *Owner = "ALİ GÜNGÖR";
23 23
24 24      // Some port values

```

```

src/Utils/octet_view.cpp
@@ -21,10 +21,12 @@ OctetView::OctetView(const uint8_t *data, size_t size) :
data(data), index(0), s
21 21
22 22      OctetString OctetView::readOctetString(int length) const
23 23      {
24 +      if (length < 0)
25 +          throw std::out_of_range("readOctetString: negative length");
24 26          if (length == 0)
25 27              return {};
26 -      else if (index + length > size)
27 -          throw std::out_of_range("Invalid arguments for readOctetString");
28 +      if (index + static_cast<size_t>(length) > size)
29 +          throw std::out_of_range("readOctetString: out of bounds");
28 30
29 31          std::vector<uint8_t> v{data + index, data + index + length};
30 32          index += length;
@@ -33,6 +35,8 @@ OctetString OctetView::readOctetString(int length) const
33 35
34 36      OctetString OctetView::readOctetString(size_t length) const
35 37      {
38 +      if (length > static_cast<size_t>(INT32_MAX))
39 +          throw std::out_of_range("readOctetString: length exceeds INT32_MAX");
36 40          return readOctetString(static_cast<int>(length));
37 41      }
38 42
@@ -43,12 +47,16 @@ OctetString OctetView::readOctetString() const

```

```

43 47
44 48     std::string OctetView::readUtf8String(int length) const
45 49     {
50 +     if (length < 0 || index + static_cast<size_t>(length) > size)
51 +         throw std::out_of_range("readUtf8String: out of bounds");
46 52         auto res = std::string(data + index, data + index + length);
47 53         index += length;
48 54         return res;
49 55     }
50 56
51 57     std::string OctetView::readUtf8String(size_t length) const
52 58     {
59 +     if (length > static_cast<size_t>(INT32_MAX))
60 +         throw std::out_of_range("readUtf8String: length exceeds INT32_MAX");
53 61         return readUtf8String(static_cast<int>(length));
54 62     }

```

src/utils/octet_view.hpp

...

```

↑... @@ -13,11 +13,11 @@
13 13
14 14     #include <stdint>
15 15     #include <cstdlib>
16 + #include <stdexcept>
16 17     #include <utility>
17 18
18 19     class OctetString;
19 20
20 - // TODO: add bound check
21 21     class OctetView
22 22     {
23 23         const uint8_t *data;
↕... @@ -30,11 +30,15 @@ class OctetView
30 30
31 31         inline octet peek() const
32 32         {
33 +         if (index >= size)
34 +             throw std::out_of_range("OctetView::peek out of bounds");
33 35         return data[index];
34 36     }
35 37

```

```

36 38     inline octet peek(int offset) const
37 39     {
40 40 +     if (offset < 0 || index + static_cast<size_t>(offset) >= size)
41 41 +     throw std::out_of_range("OctetView::peek out of bounds");
38 42     return data[index + offset];
39 43     }
40 44
@@ -50,6 +54,8 @@ class OctetView
50 54
51 55     inline octet read() const
52 56     {
57 57 +     if (index >= size)
58 58 +     throw std::out_of_range("OctetView::read out of bounds");
53 59     return data[index++];
54 60     }
55 61
@@ -123,6 +129,11 @@ class OctetView
123 129     return index < size;
124 130     }
125 131
132 132 +     inline size_t remainingSize() const
133 133 +     {
134 134 +     return size - index;
135 135 +     }
136 136 +
126 137     OctetString readOctetString(int length) const;
127 138     OctetString readOctetString(size_t length) const;
128 139     OctetString readOctetString() const;

```

Comments 0



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